

AMENDMENTS TO THE CLAIMS

This listing of claims will replace all prior versions, and listings, of claims in the application:

Listing of Claims:

- 1 1. (Currently amended) A method for matching speeds of asynchronous
2 operation between a local chip and a neighboring chip, the method comprising:
3 deriving an internal frequency signal from an internal oscillator on the
4 local chip;
5 receiving an external frequency signal from a neighboring chip;
6 comparing the internal frequency signal with the external frequency signal
7 to generate a control signal;
8 adjusting the operating speed of the local chip by applying the control
9 signal to the internal oscillator ; ~~and~~
10 wherein if the internal frequency signal is faster than the external
11 frequency signal, the control signal causes the internal frequency signal to slow
12 down;
13 wherein the neighboring chip similarly adjusts the external frequency
14 signal with respect to the internal frequency signal so that the local chip and the
15 neighboring chip operate at a substantially maximum common frequency; ~~and~~
16 wherein the local chip and the neighboring chip are coupled together in an
17 asynchronous control loop, which determines the substantially maximum common
18 frequency without reference to an external synchronous clock signal;
19 checking for a large disparity between the initial speeds of the local chip
20 and the neighboring chip that could cause a slower neighboring chip to mistake a
21 frequency signal of a faster local chip as a DC signal, and thereby cause the slower

22 neighboring chip to change its operating speed incorrectly when matching speeds
23 with the faster local chip; and
24 if the large disparity is detected, detecting on the faster local chip the
25 frequency signal of the slower neighboring chip and slowing down the frequency
26 signal of the faster local chip until eventually the control loop of the slower
27 neighboring chip can recognize the faster local chip's frequency signal;
28 wherein slowing down the faster local chip until the slower neighboring
29 chip can detect the frequency signal of the faster local chip allows the local chip
30 and the neighboring chip to match speeds even when there is a large disparity in
31 initial speeds.

1 2 (Canceled).

1 3. (Previously presented) The method of claim 1, wherein receiving the
2 external frequency signal from the neighboring chip involves receiving the
3 external frequency signal through a capacitor, an inductor, a resistor, a
4 transmission line, or a direct contact.

1 4. (Original) The method of claim 1, wherein comparing the internal
2 frequency signal with the external frequency signal involves converting the
3 internal frequency signal and external frequency signal into corresponding current
4 or voltage signals, which are proportional to the frequencies of the frequency
5 signals.

1 5. (Original) The method of claim 4,
2 wherein the internal frequency signal and the external frequency signal are
3 converted into corresponding current signals;

4 wherein comparing the internal frequency signal with the external
5 frequency signal involves comparing the two current signals to generate a
6 difference current signal; and
7 wherein the method further comprises:
8 coupling the difference current signal to an integrating capacitor to
9 produce an integrated voltage signal;
10 applying an offset current source to the integrating capacitor to
11 compensate for transistor leakages, parasitics, and/or nonlinearities; and
12 coupling the integrating capacitor to an amplifier, wherein the
13 input to the amplifier is the integrated voltage signal and the output of the
14 amplifier is the control signal.

1 6. (Original) The method of claim 1, further comprising filtering the
2 control signal to improve matching between the local chip's operating speed and
3 the neighboring chip's operating speed.

1 7. (Original) The method of claim 6, wherein filtering the control signal
2 involves coupling a filter capacitor between the control signal and ground.

1 8. (Previously presented) The method of claim 1, wherein
2 the internal frequency signal has a frequency that is a fraction of the
3 internal oscillator frequency of the local chip; and wherein
4 the external frequency signal has a frequency that is a fraction of an
5 external oscillator frequency of the neighboring chip.

1 9. (Currently amended) An apparatus for matching speeds of asynchronous
2 operation between a local chip and a neighboring chip, the apparatus comprising:

3 an internal oscillator on the local chip, from which an internal frequency
4 signal can be derived;
5 a receiving mechanism configured to receive an external frequency signal
6 from a neighboring chip;
7 a comparison mechanism configured to compare the internal frequency
8 signal with the external frequency signal to generate a control signal; ~~and~~
9 an adjusting mechanism configured to adjust the operating speed of the
10 local chip and the internal oscillator by applying the control signal to the internal
11 oscillator;
12 wherein if the internal frequency signal is faster than the external
13 frequency signal, the control signal causes the internal frequency signal to slow
14 down;
15 wherein the neighboring chip similarly adjusts the external frequency
16 signal with respect to the internal frequency signal so that the local chip and the
17 neighboring chip operate at a substantially maximum common frequency; and
18 wherein the local chip and the neighboring chip are coupled together in an
19 asynchronous control loop, which determines the substantially maximum common
20 frequency without reference to an external synchronous clock signal;
21 checking for a large disparity between the initial speeds of the local chip
22 and the neighboring chip that could cause a slower neighboring chip to mistake a
23 frequency signal of a faster local chip as a DC signal, and thereby cause the slower
24 neighboring chip to change its operating speed incorrectly when matching speeds
25 with the faster local chip; and
26 if the large disparity is detected, detecting on the faster local chip the
27 frequency signal of the slower neighboring chip and slowing down the frequency
28 signal of the faster local chip until eventually the control loop of the slower
29 neighboring chip can recognize the faster local chip's frequency signal;

30 wherein slowing down the faster local chip until the slower neighboring
31 chip can detect the frequency signal of the faster local chip allows the local chip
32 and the neighboring chip to match speeds even when there is a large disparity in
33 initial speeds.

1 10 (Canceled).

1 11. (Original) The apparatus of claim 9, wherein the receiving mechanism
2 is configured to receive the external frequency signal from the neighboring chip
3 through a capacitor, and inductor, a resistor, a transmission line, or a direct
4 contact.

1 12. (Original) The apparatus of claim 9, wherein the comparison
2 mechanism is configured to convert the internal frequency signal and the external
3 frequency signal into corresponding current or voltage signals, which are
4 proportional to the frequencies of the frequency signals.

1 13. (Original) The apparatus of claim 12,
2 wherein the external frequency signal and the internal frequency signal are
3 converted into corresponding current signals;
4 wherein the comparison mechanism is configured to compare the two
5 current signals to generate a difference current signal; and
6 wherein the apparatus further comprises:
7 an integrating capacitor to which the difference current signal is
8 coupled to produce an integrated voltage signal;
9 an offset current source applied to the integrating capacitor to
10 compensate for transistor leakages, parasitics, and/or nonlinearities; and

11 an amplifier to which the integrating capacitor is coupled, wherein
12 the input to the amplifier is the integrated voltage signal and the output of
13 the amplifier is the control signal.

1 14. (Original) The apparatus of claim 9, further comprising a filtering
2 mechanism configured to filter the control signal to improve matching between
3 the local chip's operating speed and the neighboring chip's operating speed.

1 15. (Original) The apparatus of claim 14, wherein the filtering mechanism
2 includes a filter capacitor coupled between the control signal and ground.

1 16. (Previously presented) The apparatus of claim 9, wherein
2 the internal frequency signal has a frequency that is a fraction of the
3 internal oscillator frequency of the local chip; and wherein
4 the external frequency signal has a frequency that is a fraction of an
5 external oscillator frequency of the neighboring chip.

1 17. (Currently amended) A computer system that includes a circuit for
2 matching speeds of asynchronous operation between a local chip and a
3 neighboring chip, the circuit comprising:
4 a central processing unit;
5 a semiconductor memory;
6 an internal oscillator circuit on the local chip, from which an internal
7 frequency signal can be derived;
8 a receiver circuit for receiving an external frequency signal from a
9 neighboring chip;
10 a comparison circuit for comparing the internal frequency signal with the
11 external frequency signal to generate a control signal; and

an adjustment circuit for adjusting the operating speed of the local chip and the internal oscillator by applying the control signal to and the internal oscillator;

wherein if the internal frequency signal is faster than the external frequency signal, the control signal causes the internal frequency signal to slow down;

wherein the neighboring chip similarly adjusts the external frequency signal with respect to the internal frequency signal so that the local chip and the neighboring chip operate at a substantially maximum common frequency; and

wherein the local chip and the neighboring chip are coupled together in an asynchronous control loop, which determines the substantially maximum common frequency without reference to an external synchronous clock signal; and

a detection circuit configured to check for a large disparity between the initial speeds of the local chip and the neighboring chip that could cause a slower neighboring chip to mistake a frequency signal of a faster local chip as a DC signal, and thereby cause the slower neighboring chip to change its operating speed incorrectly when matching speeds with the faster local chip;

wherein the detection circuit is further configured to, if the large disparity is detected, detect on the faster local chip the frequency signal of the slower neighboring chip and slow down the frequency signal of the faster local chip until eventually the control loop of the slower neighboring chip can recognize the faster local chip's frequency signal;

wherein slowing down the faster local chip until the slower neighboring chip can detect the frequency signal of the faster local chip allows the local chip and the neighboring chip to match speeds even when there is a large disparity in initial speeds.

18 (Canceled).

1 19. (Original) The computer system of claim 17, wherein the receiver
2 circuit is configured to receive the external frequency signal from the neighboring
3 chip through a capacitor, and inductor, a resistor, a transmission line, or a direct
4 contact.

1 20. (Original) The computer system of claim 17, wherein the comparison
2 circuit is configured to convert the internal frequency signal and the external
3 frequency signal into corresponding current or voltage signals, which are
4 proportional to the frequencies of the frequency signals.

1 21. (Original) The computer system of claim 20,
2 wherein the external frequency signal and the internal frequency signal are
3 converted into corresponding current signals;
4 wherein the comparison circuit is configured to compare the two current
5 signals to generate a difference current signal; and
6 wherein the computer system further comprises:
7 an integrating capacitor to which the difference current signal is
8 coupled to produce an integral voltage signal;
9 an offset current source applied to the integrating capacitor to
10 compensate for transistor leakages, parasitics, and/or nonlinearities; and
11 an amplifier to which the integrating capacitor is coupled, wherein
12 the input to the amplifier is the integral voltage signal and the output of the
13 amplifier is the control signal.

1 22. (Original) The computer system of claim 17, further comprising a
2 filtering circuit for filtering the control signal to improve matching between the
3 local chip's operating speed and the neighboring chip's operating speed.

1 23. (Original) The computer system of claim 22, wherein the filter circuit
2 includes a filter capacitor coupled between the control signal and ground.

1 24. (Previously presented) The computer system of claim 17, wherein
2 the internal frequency signal has a frequency that is a fraction of the
3 internal oscillator frequency of the local chip; and wherein
4 the external frequency signal has a frequency that is a fraction of an
5 external oscillator frequency of the neighboring chip.

1 25. (Previously presented) The method of claim 1, wherein adjusting the
2 frequency of the local chip involves changing the power-supply voltage of the
3 local chip.

1 26. (Previously presented) The apparatus of claim 9, wherein the adjusting
2 mechanism is configured to adjust the frequency of the local chip by changing the
3 power-supply voltage of the local chip.

1 27. (Previously presented) the computer system of claim 17, wherein the
2 adjustment circuit is configured to adjust the frequency of the local chip by
3 changing the power-supply voltage of the local chip.